My Recommendations for an Intermediate Tracker at Mid Rapidity:

The primary goal of an intermediate tracker for STAR is to provide excellent spatial resolution for finding hits to be associated with tracks. The Si trackers to be placed inside the TPC should be thin and have increasingly good resolution as the radius shrinks in order to find hits on the 'next' layer of Si without too many ambiguous hits on that layer due to projective geometry or due to background and piled-up-event issues.

All of the proposed technologies do this job; but some are better than others. For example, the HPD is the best technology for STAR at 9.2 cm radius. But it is not a complete solution, by itself, for finding hits on the HFT.

The original proposal that we considered last summer for the HPD plus IST layers had all of the strips in these systems aligned in the same direction. This yields excellent resolution in the R-phi direction but essentially none in the Z direction other than what is provided by the TPC acting alone. This configuration does a less than perfect job of finding hits to be associated with a track, and thus it limits our physics potential.

HFT1 at 2.5 cm HFT2 at 7.0 cm HPD at 9.2 cm IST1 at 12 cm IST2 at 17 cm SSD at 23 cm

The Z resolution problem can be solved by rotating one of the Si tracking layers by 90 degrees, and the IST layers are the best candidates for this rotation due to the engineering design of the other detectors (including the SSD). For a detailed discussion of the improved tracking results that can be achieved by rotating one of the IST layers, see:

http://rnc.lbl.gov/~jhthomas/public/HFT/ISTOrientation.pdf

The key issue to be resolved is that we should define the smallest possible area on the surface of the HFT for hit-finding and for associating those hits with a track. Thus, Z resolution is as important as R-Phi resolution in reducing the area to search. Yan Lu has done a nice piece of work and he has shown that rotating the outer IST layer (IST2) is better than rotating IST1 in trying to solve the Z search problem.

So IST2 is a good detector for improving the Z resolution of the intermediate tracking system.

IST1 is also a good detector, and an excellent technology. It works at 12 cm radius but it suffers from too many ambiguous hits if it is pushed into a smaller radius. See:

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http://rnc.lbl.gov/~jhthomas/public/HFT/ISTat12cm.pdf and
http://rnc.lbl.gov/~jhthomas/public/HFT/AmbiguousHits.pdf
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This problem will not be uncovered by our Monte Carlo simulations because ambiguities and ghosts are not built into the Monte Carlo simulations. They can only be estimated by a Monte Carlo after-burner or with hand calculations.

Thus, it is not a good idea to replace the HPD with an IST layer at the same radius.

It is a curious result that the IST layers at 12 and 17 cm (including rotation by 90 degrees) yield about the same hit-finding performance as the HPD plus SSD ... if you consider each of them as a stand-alone system. The reason they are equivalent, at low luminosity, is because the better R-phi resolution of the HPD is compensated for by the better Z resolution in IST2. The performance is not the same in any one dimension, but the product of the resolutions in each-of-two dimensions is about the same.

http://rnc.lbl.gov/~jhthomas/public/HFT/ACuriousResult.pdf

So the performance of the two tracking systems, considered as stand-alone systems, is roughly equivalent.

Can these systems be optimized? Yes; absolutely.

The original proposal for the IST included a layer of strips AND a layer of pads at each detector location. Overall, it was a four layer system; pads plus strips at two locations. However, the pads are not a powerful tool and they do not provide any more discrimination between ambiguous (ghost) hits on the IST layers than can be provided by the TPC, alone.

http://rnc.lbl.gov/~jhthomas/public/HFT/PadsNotNecessary.pdf

So I recommend removing the pad layers from the IST's. This will reduce the cost and complexity of the system; especially at the 17 cm radius location where the area of the detector is largest.

The HPD can also be improved if we can find a way to provide additional Z resolution for the detector system. The essential problem is that the strips of the HPD are aligned with the strips in the SSD, and this cannot be changed, and so there is very little Z resolution in the system other than what the TPC can provide, alone. This problem is most important at high luminosity and RHIC II running conditions. See:

http://rnc.lbl.gov/~jhthomas/public/HFT/ZeeTroubleWithZeeHPD.pdf

Figure 2 of this document shows that the Z resolution of the HPD+SSD tracking system can be improved.

Therefore, I recommend that we take advantage of the beautiful R-phi resolution of the HPD and supplement it with a stripped down and economical IST layer at 17 cm. This is my recommendation for an intermediate tracker at mid-rapidity for STAR.

The IST layer at 12 cm is not needed because the pointing resolution of the HPD is better than IST1 and the HPD does not suffer from a problem with ambiguous and ghost hits. Furthermore, the pads on IST2 are not needed, as mentioned above.

I believe that this is the best system we can build. It has the best performance, the technologies are within reach, and the costs have been minimized by eliminating thee layers of Silicon from the system that we proposed last summer.

Performance of HFT1 + HFT2 + HPD + IST2(no pads) + SSD + TPC :

It is interesting to compare the performance of the **HPD+IST2** tracker to the HPD+SSD and the IST1+IST2 trackers as pointing devices for the HFT.

I will do this under fairly conservative conditions (meaning difficult conditions) ... which means RHIC II running conditions and Au-Au minbias collisions. The full parameter set is listed at the end of this note.

As shown in Figure 1, The R-Phi resolution of the HPD+SSD system is better than the IST1+IST2 system because the HPD has very fine strips (50 microns) and it is closer to the surface of the HFT and thus has a shorter lever arm to amplify the effects of MCS. Also, the HPD does not suffer from a serious occupancy problem. The strips are relatively short (425 μ m) compared to the length of the strips in the IST (3.8 cm).

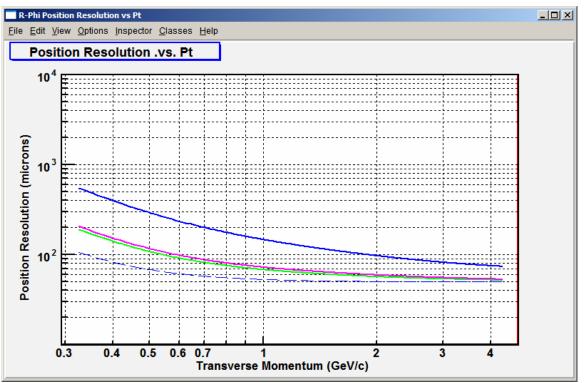


Figure 1: The blue lines show the R-Phi pointing resolution for the IST1+IST2 tracker on the outer surface of the HFT. The green lines show the resolution of the HPD+SSD tracker, and the magenta lines shows the pointing resolution for the HPD+IST2.

However, the relative performance of the detectors is reversed when we consider the pointing resolution in the Z direction. The IST1+IST2 tracker achieves relatively good Z resolution because the IST2 layer is assumed to be rotated by 90 degrees. Figure 2 is a graph of the Z pointing resolution for all three cases, including the HFT+IST2. As shown in the figure, zee problem with the HPD+SSD is that zee strips in the HPD are aligned with zee strips in the SSD ... and so the Z resolution for the HPD is constant, as a function of pt. The Magenta line in the figure shows the improvement that is possible with an IST layer (without pads and rotated by 90 degrees) located at 17 cm radius.

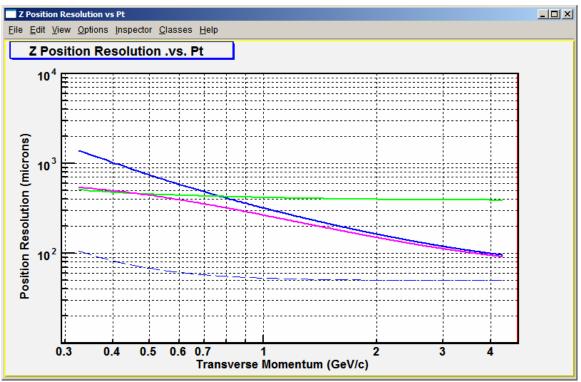


Figure 2: The blue line shows the Z pointing resolution for the IST1+IST2 tracker onto the surface of the HFT. The green lines show the pointing resolution of the HPD+SSD tracker and the magenta line shows the improvement than can be achieved by adding IST2. The HPD+IST2+SSD tracker is the best combination.

The dashed line at the bottom of figures one and two is a reference line to guide the eye. It is a theoretical estimate of the HFT vertex resolution if the HFT could act alone ... no other detectors, and no other sources of MCS.

Is the poor Z resolution of the HPD+SSD important? Yes, it turns out to be noticeable. The reason it become important is because the intermediate tracker is used to define an 'area' on the outer surface of the HFT and this area is searched for good hits. The area is elliptical in shape, where $A = 2\pi R_{R-Phi} R_Z$, and if this area is large enough relative to the occupancy and pileup in the HFT, then the tracker will find a false hit before finding the right hit. The effects of the changing Z resolution can be seen in Figure 3 where graph shows the pointing resolution for the various tracking systems and estimate the D0's

reconstruction efficiencies. The inefficiencies due to poor Z resolution are even more important for the Λ_c because it has a three body final state.

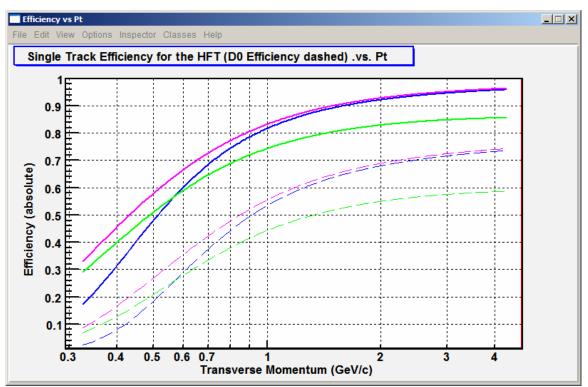


Figure 4: The solid blue line shows the efficiency for finding a kaon in the HFT with the IST1+IST2 tracker. The green line shows the efficiency for finding a kaon with the HPD+SSD tracker. The magenta line shows the efficiency for finding a kaon with the HPD+IST2 (rotated and without pads) tracker. The HPD+IST2 tracker is the best. The dashed lines represent the square of the solid lines (times 0.8 to displace the curves) and is a very crude estimate of the D0 track finding efficiency in each case. The region of most interest is from 750 MeV to 1 GeV.

Summary:

The HPD and IST detectors are beautiful examples of modern tracking technology. By combining the best of both technologies, a powerful pointing device for STAR can be built. The best combination in terms of performance and cost is to build the HPD in combination with one layer of the IST at 17 cm radius.

The layer at 17 cm should be rotated by 90 degrees, and the pads can be removed. This removes three layers of Si from the proposal that we discussed last summer and yields a thin, low radiation length, cost efficient, but high performance system for doing Heavy Flavor physics in STAR.

The HPD+IST2 tracker is a good system.

Additional Comments:

An interesting feature of a high resolution Si detector system, is that the intrinsic resolution is so high, in each layer, that the resolution on the next layer of tracking is dominated by MCS in the current layer. The tracking performance before the current layer does not play a large role in determining the pointing resolution onto the layer after the current layer. The previous layers are employed to find hits on the current layer, but once found, do not play a dominant role thereafter. This feature is unique to high resolution detectors and this thinking is different than the traditional idea that stacking multiple detectors improves the pointing resolution of the system by a strong function of N, where N is the number of layers. In a closely stacked Si tracker, it is entirely possible to make the pointing resolution of the system worse by adding an additional layer.

Low resolution detectors can assist a high resolution Si tracker because the low resolution detectors may provide important directional information (angle constraint) if the detector elements are distributed over a large distance. The STAR TPC is a good example; it provides a long track segment to seed the search for a track. The TPC does not provide tight translational constraints on the position of a hit at any radius ... but it does provide a tight angular constraint on the direction that the track can take. This means that every track segment that starts in the TPC looks like a stiff track to the Si detectors, independent of momentum. The track segment can only go through the Si detectors from a certain direction and so the Si detectors are most useful in constraining the translational location of the track. Thus, radial location of the Si detectors is not as important as it would be if the TPC was not included in the tracking system.

<pre>#define #define #define</pre>	Mass BFIELD AvgRapidity Luminosity Sigma dNdEta CrossSection IntegrationTime BackgroundMultiplier SiScaleFactor EfficiencySearchFlag	0.540 0.5 0.5 1.e28 15.0 170 10 0.2 4.0 1.0 0	<pre>// Mass of the test particle in // Tesla (test data taken at 0.25 // Avg rapidity, MCS calc is a // Luminosity of the beam (RHIC I == // Size of the interaction diamond // Multiplicity per unit Eta (AuAu // Cross section for event under // Integration time for HFT chips (// Increase multiplicity in detector // For scaling Si pad sizes. (eg // Define search method. ChiSquare =</pre>
// Most likely	/ Detector parameters you	may want to	tune are in the block starting here:
#define	VtxResolution	0.3000	// cm Test data wants 3 mm vertex
#define	VtxResolutionZ	0.3000	// cm Test data wants 3 mm vertex
#define	NewVtxResolution	0.0300	<pre>// cm NewVertex to study effect of a</pre>
#define	NewVtxResolutionZ	0.0300	<pre>// cm NewVertex to study effect of a</pre>
#define	RefitVtxResolution	0.0030	// cm Refit Vertex to study effect
#define	RefitVtxResolutionZ	0.0030	// cm Refit Vertex to study effect
#define	BeamPipelResolution	RIDICULOUS	// Beampipe is not active as a
#define #define	HftlResolution HftlResolutionZ	0.0030 0.0030	// cm 30 x 30 micron pixels // cm 30 x 30 micron pixels
#define	Hft2Resolution	0.0030	// cm 30 x 30 micron pixels
#define	Hft2ResolutionZ	0.0030	// cm 30 x 30 micron pixels

Parameters used in these calculations:

#define	BeamPipe2Resolution	RIDICULOUS	// Beampipe is not active as a
#define	HpdResolution	0.0050	// cm 50 x 425 micron pixels
#define	HpdResolutionZ	0.0425	// cm 50 x 425 micron pixels
#define	IstlResolution	0.0060	<pre>// cm 60 x 1920 micron pixels Z // cm 60 x 1920 micron pixels // cm 60 x 1920 micron pixels // cm 60 x 1920 micron pixels</pre>
#define	IstlResolutionZ	0.1920	
//#define	IstlResolution	0.1920	
//#define	IstlResolutionZ	0.0060	
//#define	Ist2Resolution	0.0060	<pre>// cm 60 x 1920 micron pixels // cm 60 x 1920 micron pixels // cm 60 x 1920 micron pixels // cm 60 x 1920 micron pixels</pre>
//#define	Ist2ResolutionZ	0.1920	
#define	Ist2Resolution	0.1920	
#define	Ist2ResolutionZ	0.0060	
#define	SsdResolution	0.0095	// cm 95 x 4200 microns double
#define	SsdResolutionZ	0.2700	// cm 95 x 4200 microns double
#define	IFCResolution	RIDICULOUS	// IFC is not active as a detector
#define	TpcResolution	0.0575	// cm 600 x 1500 micronsTest
#define	TpcResolutionZ	0.1500	// cm 600 x 1500 micronsTest

// End of 'most likely' block, but there are more parameters, below.

#define	VtxIndex	0
#define	BeamPipelIndex	1
#define	HftlIndex	2
#define	Hft2Index	3
#define	BeamPipe2Index	4
#define	HpdIndex	5
#define	IstlIndex	6
#define	Ist2Index	7
#define	SsdIndex	8
#define	IFCIndex	9
#define	TpcIndex	10
#define	VtxThickness	0.0000 // % Radiation Lengths
#define	BeamPipelThickness	0.0015 // % Radiation Lengths (as in 0.01 == 1%)
#define	Hft1Thickness	0.0028 // % Radiation Lengths (0.0028 new 0.0036
#define	Hft2Thickness	0.0028 // % Radiation Lengths (0.0028 new 0.0036
#define	BeamPipe2Thickness	0.0015 // % Radiation Lengths
#define	HpdThickness	0.0100 // % Radiation Lengths
#define	IstlThickness	0.0150 // % Radiation Lengths
#define	Ist2Thickness	0.0150 // % Radiation Lengths
#define	SsdThickness	0.0100 // % Radiation Lengths
#define	IFCThickness	0.0052 // % Radiation Lengths
#define	TpcAvqThickness	0.00026 // % Radiation Lengths Average per
#define	VtxRadius	0.0 // cm
#define	BeamPipelRadius	2.05 // cm (2.05 new 1.50 old)
#define	HftlRadius	2.50 // cm (2.5 new 1.55 old)
#define	Hft2Radius	7.00 // cm (7.0 new 5.00 old)
#define	BeamPipe2Radius	8.55 // cm (8.55 new 6.05 old)
#define	HpdRadius	9.2 // cm (9.2 HPD, 6.0 SVT)
#define	IstlRadius	12.0 // cm (12.0 IST,10.0 SVT, option 9.5 IST)
#define	Ist2Radius	17.0 // cm (17.0 IST,14.0 SVT)
#define	SsdRadius	23.0 // cm
#define	IFCRadius	47.25 // cm Middle-Radius of the IFC its
#define	TpcInnerRadialPitch1	4.8 // cm
#define	TpcInnerRadialPitch8	5.2 // cm
#define	TpcOuterRadialPitch	2.0 // cm
#define	TpcInnerPadWidth	0.285 // cm
#define	TpcOuterPadWidth	0.620 // cm
#define	InnerRowsl	8
#define	InnerRows8	5
#define	InnerRows	(InnerRows1+InnerRows8)
#define	OuterRows	32
#define	TpcRows	(InnerRows1 + InnerRows8 + OuterRows)
#define	RowOneRadius	60.0 // cm